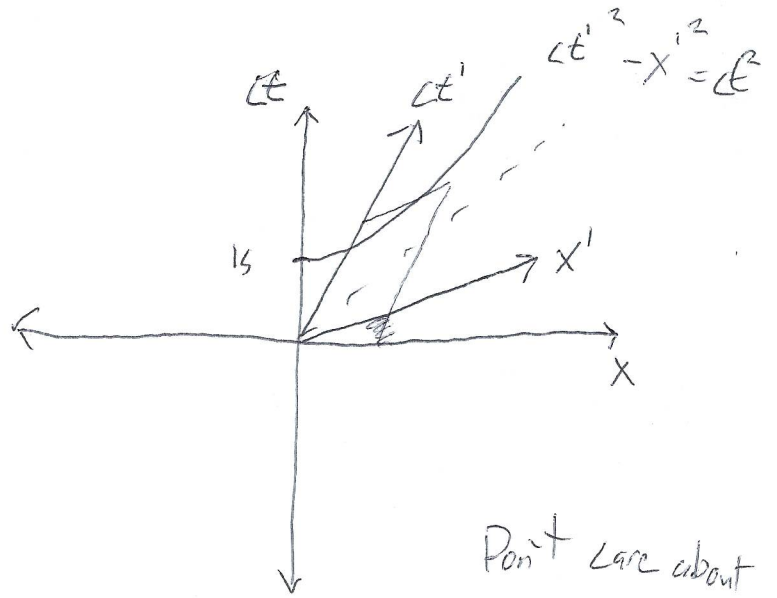
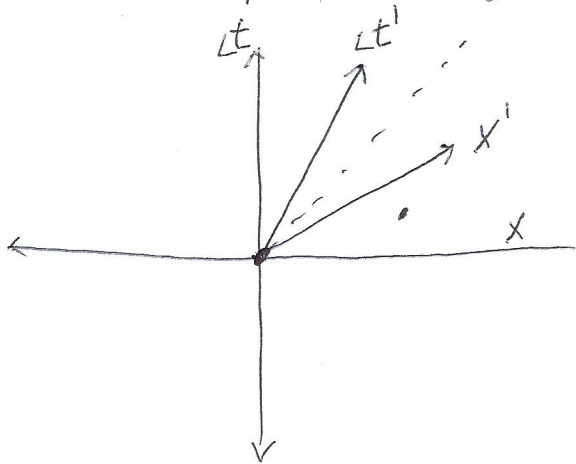
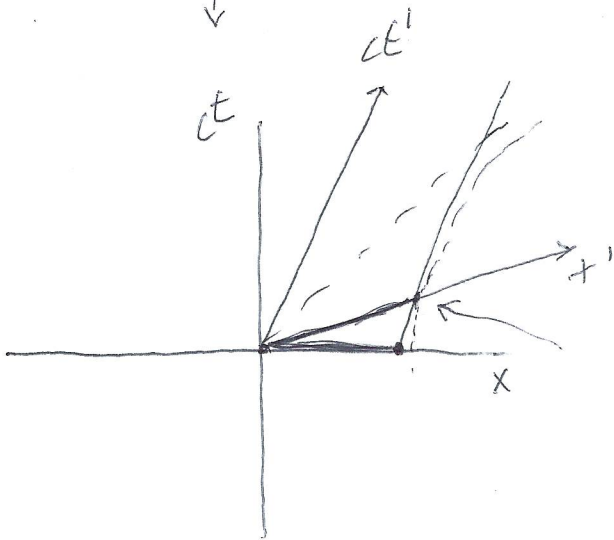
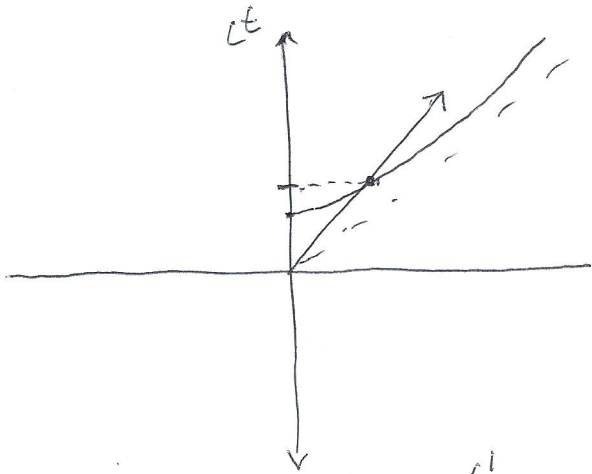


Phys 110B 14 Sep 20

Minkowski Spacetime Diagrams



Don't care about
the geometry of
the page
Not Euclidean



length at
rest frame

\vec{X} dX^μ is a contravariant 4-vector

$$\vec{v} = \frac{d\vec{X}}{dt}$$

ds^2 is invariant $\Rightarrow d\tau$ is invariant

$$\vec{a} = \frac{d\vec{v}}{dt} = \frac{d^2 \vec{X}}{dt^2}$$

$\frac{dX^\mu}{d\tau}$ is a 4-vector 4-velocity

"proper velocity"
↑
bad notation

$$\frac{dX^\mu}{d\tau} = \frac{dt}{d\tau} \frac{dX^\mu}{dt} = \gamma \frac{dX^\mu}{dt}$$

$$d\tau = \frac{dt}{\gamma} \quad u = \begin{bmatrix} c\tau \\ \vec{v}\tau \end{bmatrix}$$

$$u \cdot u = \frac{dX^\mu}{d\tau} \frac{dX_\mu}{d\tau} = \frac{dX^\mu}{d\tau} \eta_{\mu\nu} \frac{dX^\nu}{d\tau}$$

$$\frac{dX \cdot d\bar{X}}{(d\tau)^2} = \frac{ds^2}{(d\tau)^2} = - \frac{(d\tau)^2}{(d\tau)^2} = -1$$

material particle
($m > 0$)

$$u \cdot u = -1$$

A^μ mean something else

$$4\text{-acceleration} \cdot \frac{d}{d\tau} u^\mu = \frac{d^2}{d\tau^2} X^\mu = A^\mu$$

$$u \cdot A = 0$$

$$u \cdot u = -1 \quad u^\mu u_\mu = -1$$

$$\frac{d}{d\tau} (u^\mu u_\mu) = \frac{d}{d\tau} (-1) = 0$$

$$u^\mu \frac{d}{d\tau} u_\mu + \frac{d}{d\tau} u^\mu u_\mu = u^\mu a_\mu + a^\mu u_\mu = 2u^\mu a_\mu = 0 \Rightarrow u^\mu a_\mu = 0$$

$$\frac{d}{dt} \cdot \frac{d}{dt} = ?$$

$$\sqrt{a_\mu a^\mu} = \begin{matrix} \text{magnitude of} \\ \text{proper acceleration} \end{matrix}$$

"g-force" in the instantaneous rest frame

waves?

ω angular frequency

$$\omega = \omega(\vec{k})$$

wave $A e^{i\theta(x,t)}$

\vec{k} 3-wave vector

↑
dispersion relation

$$\theta(x,t) = \vec{k} \cdot \vec{x} - \omega t$$

phase: a number of peaks

θ must be invariant

$$\theta = \underbrace{\vec{k}}_{\omega/c} \cdot \underbrace{\vec{x}}_{\vec{x}} = -\frac{\omega}{c} ct + \vec{k} \cdot \vec{x} = -\omega t + \vec{k} \cdot \vec{x}$$

$$\begin{matrix} \downarrow \\ \left[\begin{matrix} \omega/c \\ \vec{k} \end{matrix} \right] \end{matrix} \rightarrow \begin{matrix} [ct] \\ [\vec{x}] \end{matrix}$$

4-wavevector

$$K^\mu \quad X^\mu$$

$$K'_\mu = \Lambda K_\mu$$

relativistic doppler shifts

"headlighting effects"

$$\theta = K_\mu X^\mu$$

Planck - Einstein relations

$$\begin{matrix} \cancel{E = \hbar \omega} & \cancel{\vec{p} = \hbar \vec{k}} \\ E = \hbar \omega & \vec{p} = \hbar \vec{k} \propto \vec{v} \end{matrix}$$

$\hbar K^\mu = P^\mu$ energy - momentum 4-vector

$$P_m = \begin{bmatrix} E/c \\ \vec{p} \end{bmatrix} = \begin{bmatrix} \frac{mc^2 \gamma}{c} \\ mc \gamma \vec{\beta} \end{bmatrix} \quad \begin{array}{l} E = \gamma mc^2 = \text{relativistic energy} \\ \vec{p} = mc \gamma \vec{\beta} = \gamma m \vec{v} = \text{relativistic 3-momentum} \end{array}$$

1. covariant (transform nicely)

2. reduce to Newton in the low-velocity limit

3. Preserve conservation laws

$|\vec{v}| \ll c$ then $\vec{p} = m\vec{v} + \dots$ taylor expand $\gamma = \frac{1}{\sqrt{1-\beta^2}}$

$$E = \underbrace{mc^2}_{\text{rest mass energy}} + \frac{1}{2} m |\vec{v}|^2 + \dots$$

relativistic kinetic energy $T = E - mc^2 = (\gamma - 1)mc^2$

$$P^\mu = m U^\mu = m \frac{d}{d\tau} X^\mu$$

↑
4-vector

m = rest mass * is a Lorentz scalar/invariant
"invariant" the kind of particle, same with "q"

γm relativistic mass } Not a good approach
 $\vec{p} = \gamma m \vec{v}$

$$\vec{p} \cdot \vec{p} = -\frac{E^2}{c^2} + |\vec{p}|^2$$

$$m\vec{U} \cdot (m\vec{U})$$

$$m^2(-1)$$

$$E^2 = c^2 |\vec{p}|^2 + m^2 c^4$$

$$E = \gamma m c^2$$

$$\vec{p} = \gamma m c \vec{\beta}$$

$$\frac{c\vec{p}}{E} = \frac{\gamma m c^2 \vec{\beta}}{\gamma m c^2} = \vec{\beta} = \frac{c\vec{p}}{E}$$

$$\vec{\beta} = \frac{c\vec{p}}{E}$$

dynamics?

Newton's 2nd Law

$$\vec{f} = m\vec{a} = \frac{d}{dt} \vec{p}$$

$$\frac{d}{dt} \vec{p} = \vec{f} \quad \leftarrow \text{3-force}$$

$$\vec{p} = \gamma m \vec{v}$$

$$\frac{d}{dt} \vec{p} = \vec{f}$$

$$\frac{d}{dt} p^\mu = F^\mu$$

4-vector

4-force

Minkowski Force

