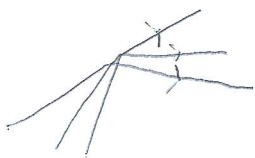


$$\vec{V} = v^i b_i = \sum_i v^i b_i$$

Coordinate basis

$$\vec{R}(q^1, q^2, q^3, \dots)$$

Choose basis so coefficients transform as a rank-1 tensor
Coordinate basis



coordinate curves

Vary 1 coordinate and leave others fixed

coordinate basis vectors = tangent vectors to coordinate curves

$$\vec{b}_i = \frac{\partial \vec{R}}{\partial q^i} \quad \text{i-th coordinate basis vector}$$

$$d\vec{R} = \frac{\partial \vec{R}}{\partial q^i} dq^i = \vec{b}_i dq^i$$

$$ds^2 = d\vec{R} \cdot d\vec{R} = (\vec{b}_i dq^i) \cdot (\vec{b}_j dq^j) = (\vec{b}_i \cdot \vec{b}_j) dq^i dq^j$$

spacetime interval

metric tensor

Covariant Rank-2 tensor

Symmetric

metric space's g is positive definite

pseudo-Riemannian manifold g is no longer positive definite

$$\vec{V} = v^i \vec{b}_i$$

$$\vec{V} \cdot \vec{b}_j = v^i \vec{b}_i \cdot \vec{b}_j = v^i g_{ij} \quad \text{if coordinates are orthonormal } g_{ij} \text{ is diagonal}$$

dual coordinate basis

$$\text{define } \vec{b}^j \cdot \vec{b}_i = \delta^j_i = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{otherwise} \end{cases}$$

dual basis coordinate basis

$$\vec{V} = V^i b_i$$

$$\vec{b}^j \cdot \vec{V} = \vec{b}^j \cdot (V^i \vec{b}_i) = V^i (\vec{b}^j \cdot \vec{b}_i) = V^i \delta_i^j = V^j$$

$$\vec{V} = V_j \vec{b}^j$$

$$\vec{b}_i \cdot \vec{V} = \vec{b}_i \cdot (V_j \vec{b}^j) = V_j \vec{b}_i \cdot \vec{b}^j = V_j \delta_i^j = V_i$$

$$V^i \vec{b}_i = \vec{V} = V_j \vec{b}^j \quad \text{some relationship needed, is metric tensor}$$

define g^{ik} so that $g^{ik} g_{kj} = \delta^i_j$

$$\vec{b}^i = g^{ij} \vec{b}_j \quad \vec{b}_i = g_{ij} \vec{b}^j$$

$$\vec{V} = V_i \vec{b}^i = (V_i g^{ij}) \vec{b}_j = V^j \vec{b}_j$$

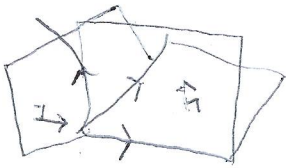
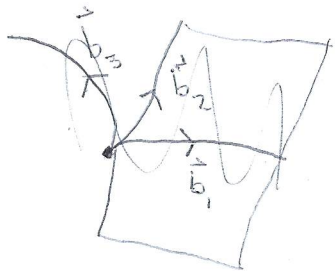
$$V^j = g^{ji} V_i \quad V_j = g_{ji} V^i$$

$$g_{ij} A^j_k = A_{ik}$$

$$\vec{x}^T A \vec{y}$$

$$A \vec{A}(\vec{b}_j, \vec{b}_k) = A_{jk}$$

$$\vec{A}(V^j \vec{b}_j, V^k \vec{b}_k) = V^j V^k A_{jk}$$



coordinate surface
= level surfaces of
each coordinate

$$\vec{b}^i = \nabla q^i = \frac{\partial q^i}{\partial R}$$

$$\vec{b}^i \cdot \vec{b}_j = \frac{\partial q^i}{\partial R} \cdot \frac{\partial R}{\partial q^j} = \frac{\partial q^i}{\partial q^j} = \delta^i_j$$

$$g_{ij} = \vec{b}_i \cdot \vec{b}_j$$

$$g^{ij} = \text{inverse}$$

$$g^{ij} = g^{ik} g_{kj} = \delta^i_j$$

$$g^{ij} = g^{il} g_{lj} = g^{il} \delta^l_j = g^{ij} = g^{ji}$$

$$\vec{u} \cdot \vec{w} = (u^i \vec{b}_i) \cdot (w^j \vec{b}_j) = u^i w^j (\vec{b}_i \cdot \vec{b}_j) = g_{ij} u^i w^j$$

$$\vec{u} \cdot \vec{w} = u^i g_{ij} w^j = w^j g_{ji} u^i = u^i w_j = u_i w^i$$

$$i \leftrightarrow j$$

rank-0 tensor
scalar

$$\vec{b}_i = \frac{\partial \vec{R}}{\partial x^i} = \frac{\partial x^j}{\partial x^i} \frac{\partial \vec{R}}{\partial x^j} = \frac{\partial x^j}{\partial x^i} b_j$$

$$\vec{u} \cdot \vec{w} = u_i w^i = u^i w_i$$

$$u_i =$$

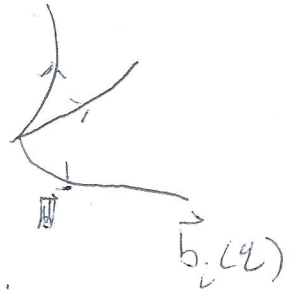
transform
with inverse
and regular
Jacobian

$$x^j$$

Christoffel symbols

not tensors

$$\frac{\partial}{\partial x^i} b^k = \Gamma^k_{ij}$$



Define orthonormal bases

$$\vec{b}^k(\vec{b}_j) = \vec{b}^k \cdot \vec{b}_j$$

$$(w_k \vec{b}^k) \cdot (v^j \vec{b}_j) = w_k v^j \vec{b}^k \cdot \vec{b}_j = w_i v^i$$

