# Analytic Mechanics Lecture 4

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## (Weak) Equivalence Principle

The ratio of inertial mass and gravitational mass has been calculate to high precision

$$
\frac{m_i}{m_g} = 1 \pm 10^{-12}
$$

This suggests that the inertial mass and gravitational mass are probably equivalent and that the mass is independent of composition.

$$
m_i = m_g = m
$$

### Dropping a Particle with Air Resistance and Gravity

We can consider a particle falling with only two forces acting on it: air resistance and gravity. We can then say the net force is

$$
\boldsymbol{F_{tot}} = \boldsymbol{F_g} + \boldsymbol{F_r} = (mg - mkv^2)\hat{\boldsymbol{y}} = m\boldsymbol{a} = ma\hat{\boldsymbol{y}}
$$

We are going to find our equation of motion to get a better feel for what is going on in this system.

$$
ma = mg - mkv2
$$

$$
a = g - kv2 = \frac{dv}{dt} = \frac{dv}{dy}\frac{dy}{dt} = v\frac{dv}{dy}
$$

This last piece can be rewritten as

$$
v\frac{dv}{dy} = \frac{1}{2}\frac{dv^2}{dy}
$$

This gives us our general solution (using  $\beta = \frac{-g}{k}$  $\frac{-g}{k}$ 

$$
v^2 = \beta e^{-2ky} - \beta
$$

## Momentum

$$
\boldsymbol{F} = m\boldsymbol{a} = m\frac{d\boldsymbol{v}}{dt}
$$

If m is constant, we can rewrite this equation as

$$
\boldsymbol{F} = \frac{d\boldsymbol{p}}{dt}
$$

## Impulse

Impulse will be the change in momentum.

$$
\Delta \boldsymbol{p} = \boldsymbol{p_f} - \boldsymbol{p_i} = \int_{t_i}^{t_f} \boldsymbol{F} dt = \text{impulse}
$$

If we had some force acting on some object for a short period of time

$$
\boldsymbol{F} = \begin{cases} \boldsymbol{F_0} & [t, t + \Delta t] \\ 0 & otherwise \end{cases}
$$

The impulse will be the integral of this equation.

$$
\int_{t}^{t+\Delta t} \boldsymbol{F_0} dt = \boldsymbol{F_0} \Delta t
$$

To find the distance travelled, we need to find the average force.

$$
\langle F \rangle = \frac{\int_t^{t + \Delta t} F_0 dt}{\Delta t} = \frac{F_0 \Delta t}{\Delta t} = F_0
$$

The average acceleration would then be

$$
\langle a\rangle=\frac{F_0}{m}
$$

We can then find the distance travelled as

$$
\Delta x = \frac{1}{2} \langle a \rangle (\Delta t)^2 = \frac{F_0}{2m} (\Delta t)^2
$$

$$
\lim_{t \to \infty} \Delta x = 0
$$

This means that the object doesn't move, even if our applied force is not zero.

## Work and Energy

Work can be defined as a force  $\boldsymbol{F}$  acting on an object along some path  $\Gamma$ .

$$
W = \int_{\Gamma} \boldsymbol{F} \cdot d\boldsymbol{l}
$$

 $dl$  is our line element is expressed in cartesian coordinates:

$$
d\bm{l}=dx_i\hat{\bm{x}}
$$

Cylindrical:

$$
d\bm{l} = dr\hat{\bm{r}} + rd\hat{\bm{\phi}} + dz\hat{\bm{z}}
$$

Spherical:

$$
d\bm{l}=dr\hat{\bm{r}}+r d\theta\hat{\bm{\theta}}+r\sin(\theta)d\phi\hat{\bm{\phi}}
$$

Let's complete the integral and see if we can get work as a function of velocity.

$$
W = \int_{\Gamma} \mathbf{F} \cdot d\mathbf{l} = \int_{\Gamma} \frac{d(m\mathbf{v})}{dt} \cdot \mathbf{v} dt = m \int_{\Gamma} \frac{d\mathbf{v}}{dt} \cdot \mathbf{v} dt = m \int_{\Gamma} d\mathbf{v} \cdot \mathbf{v}
$$

$$
= \frac{d(\mathbf{v} \cdot \mathbf{v})}{dt} = \mathbf{v} \cdot \frac{d\mathbf{v}}{dt} + \frac{d\mathbf{v}}{dt} \cdot \mathbf{v}
$$

Using a magical trick where we can "cancel out" the  $dt$ 's, we get

 $2d\boldsymbol{v}\cdot\boldsymbol{v}=d(\boldsymbol{v}\cdot\boldsymbol{v})$ 

$$
W = \frac{m}{2} \int_{\Gamma} d(\boldsymbol{v} \cdot \boldsymbol{v}) = \frac{-1}{2} m (v_b^2 - v_a^2)
$$

We can see now that work is the change in kinetic energy.